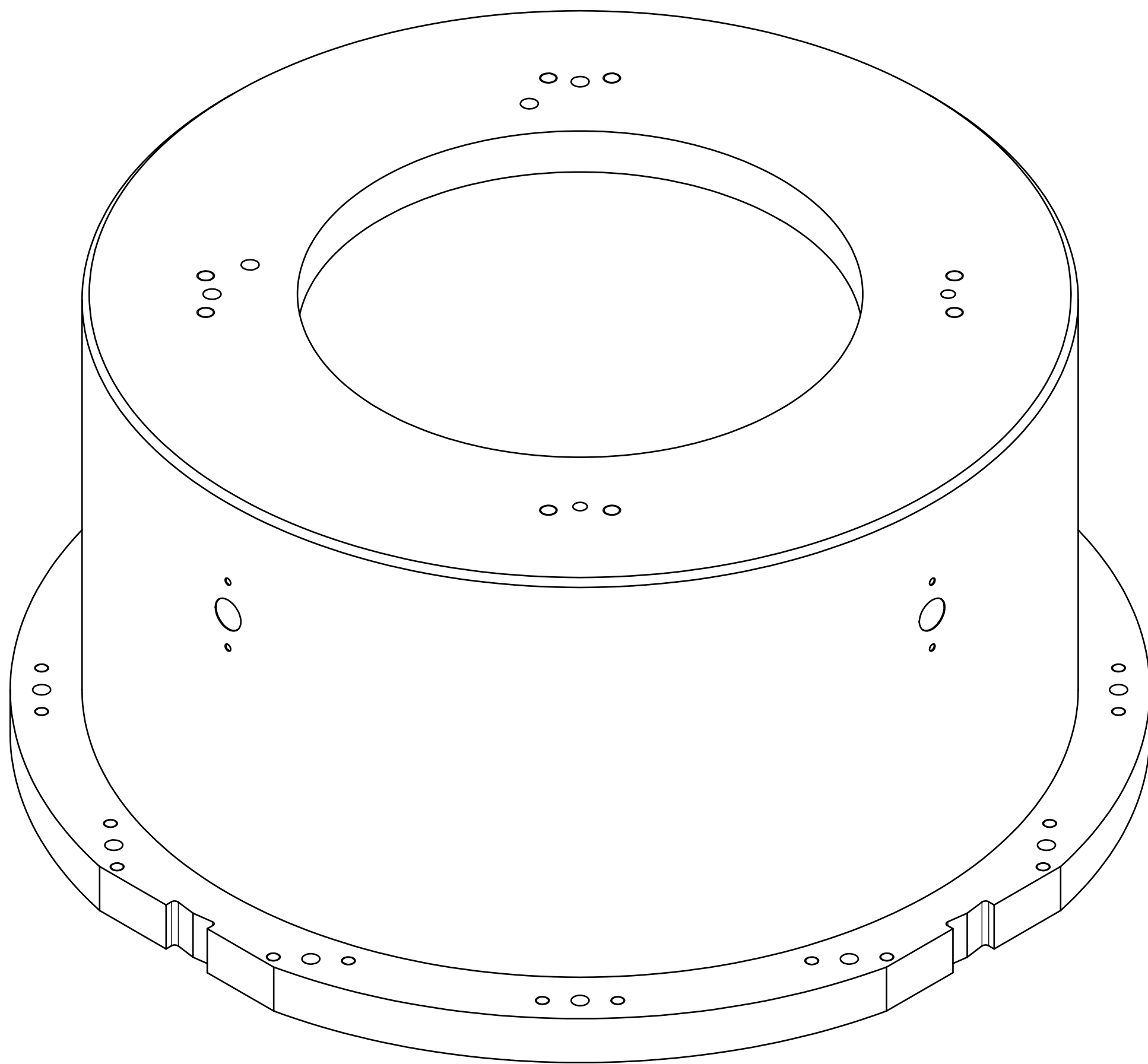
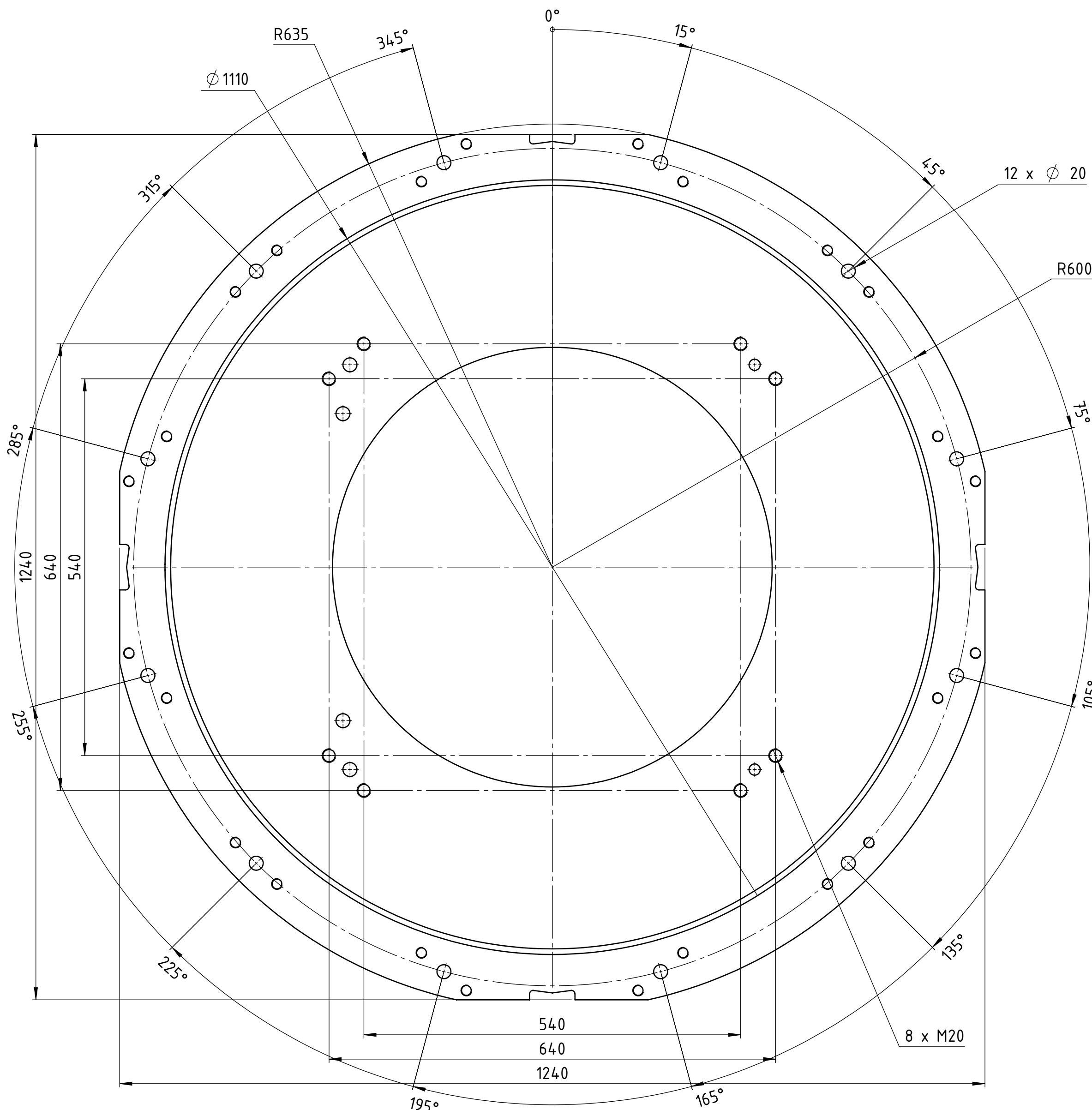
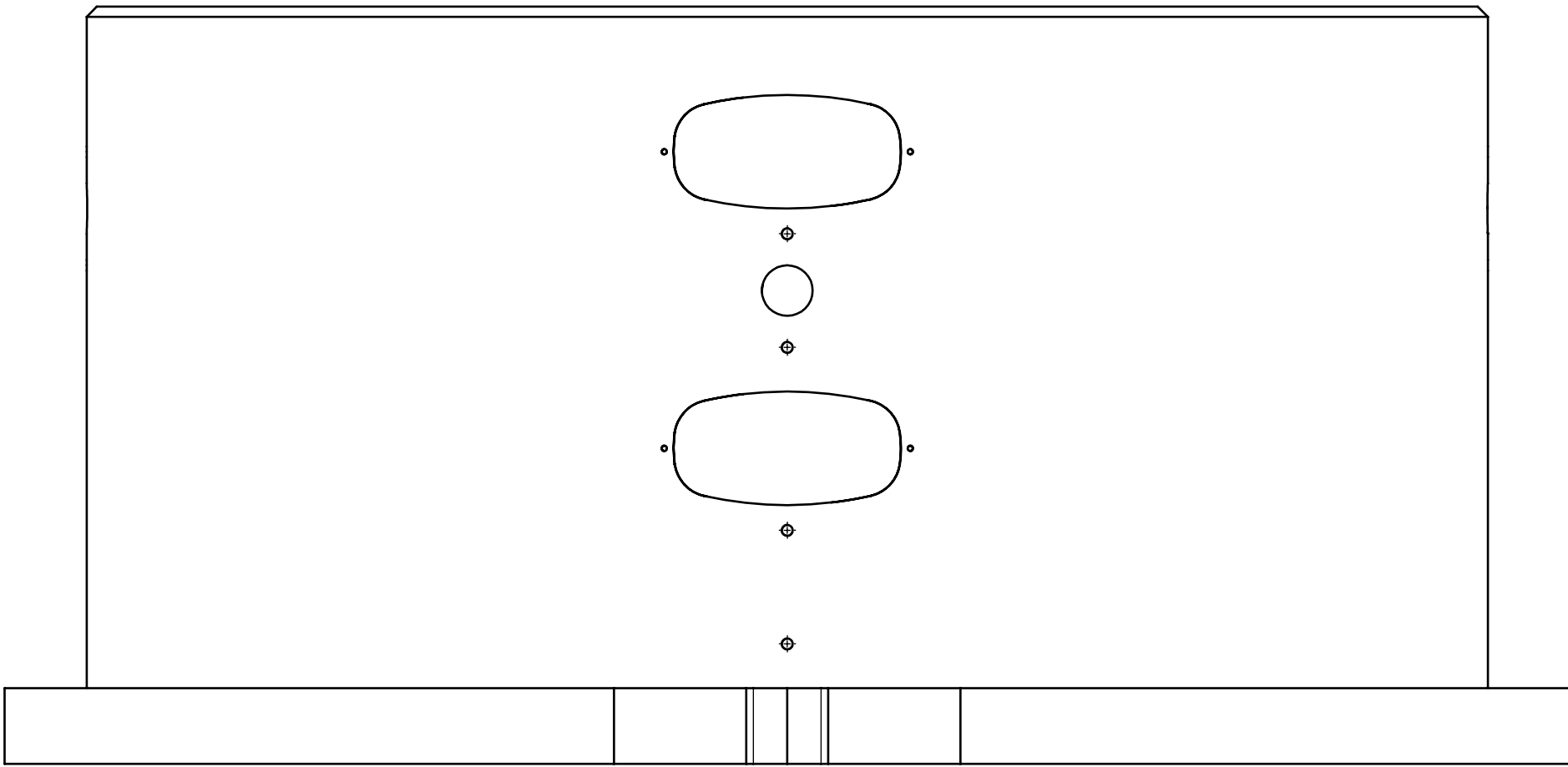
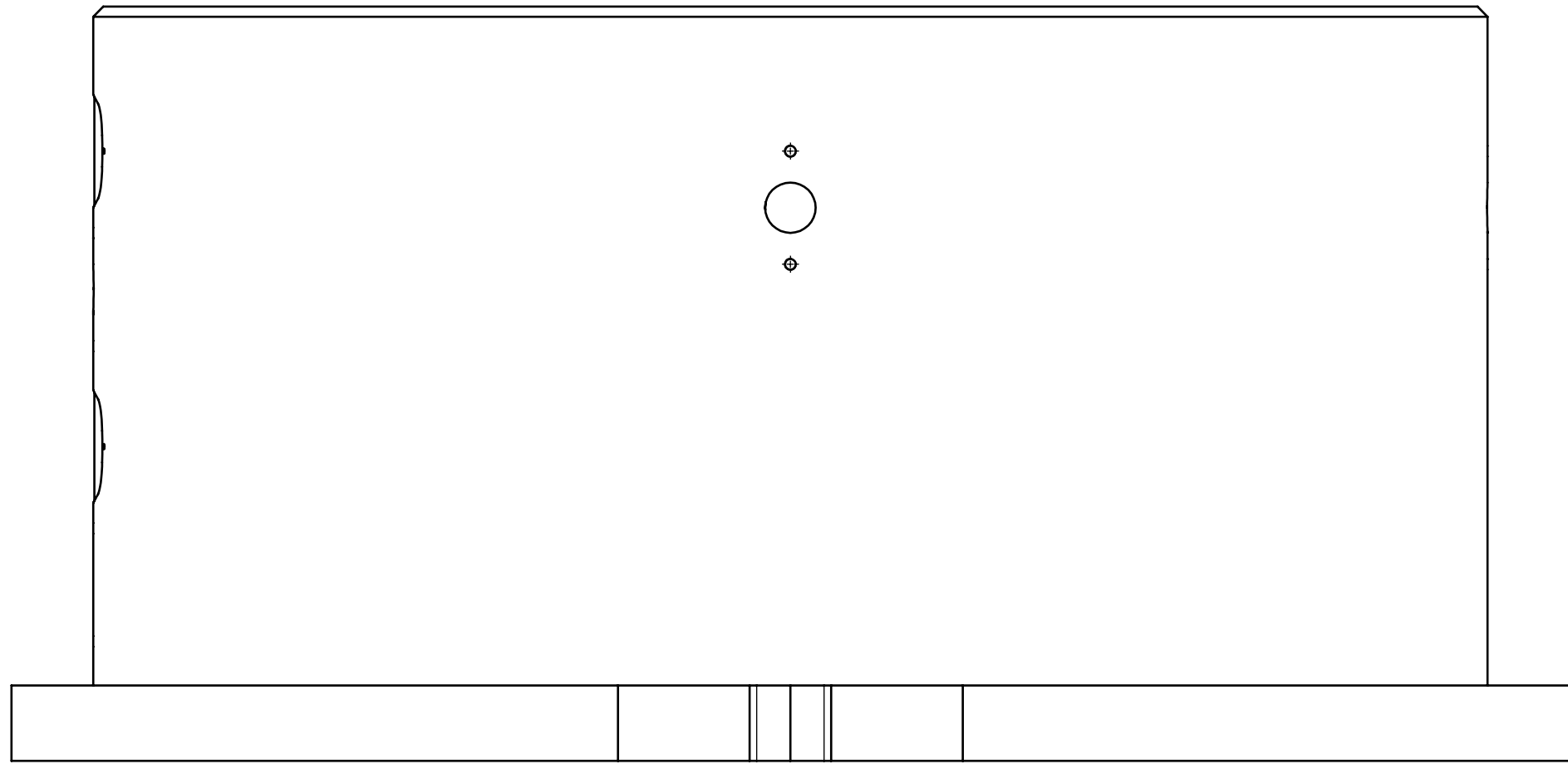
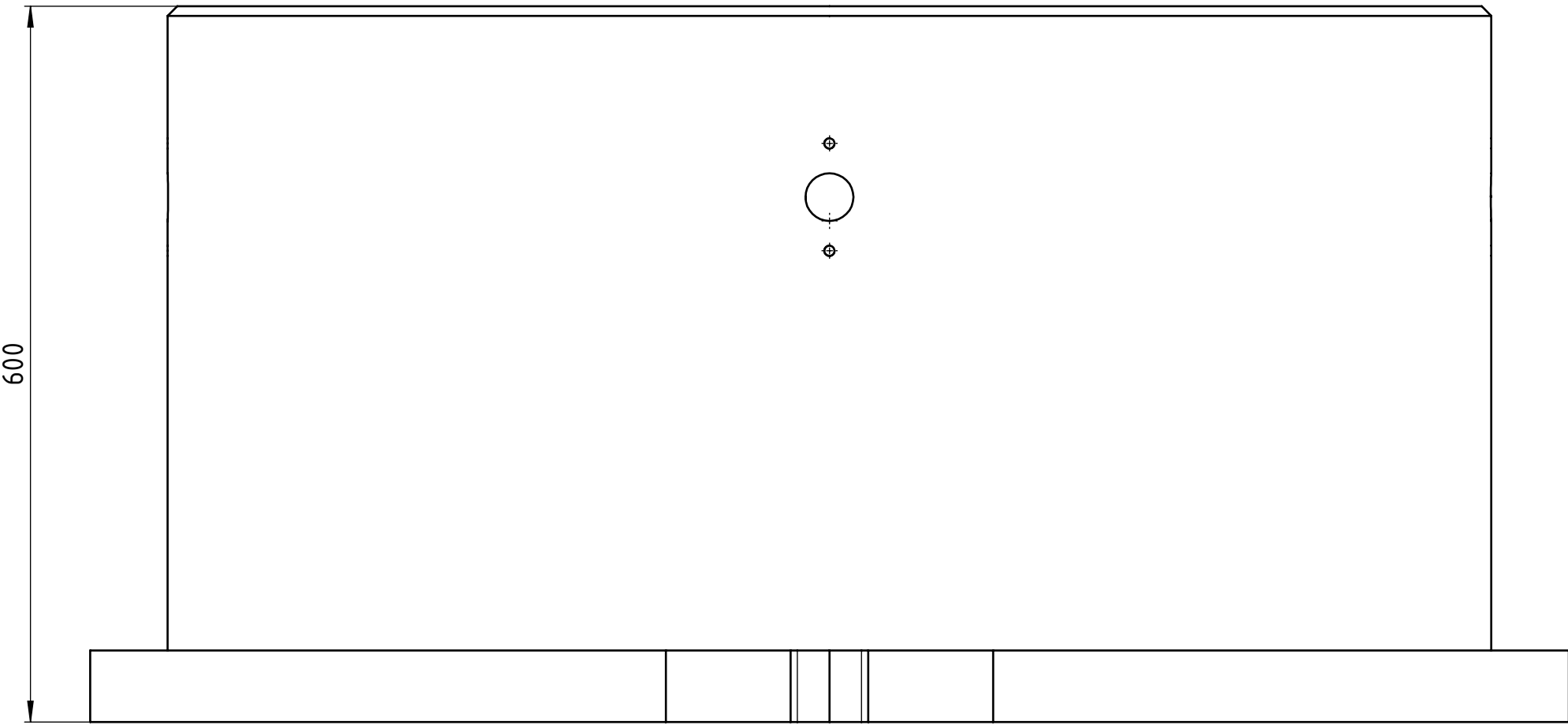
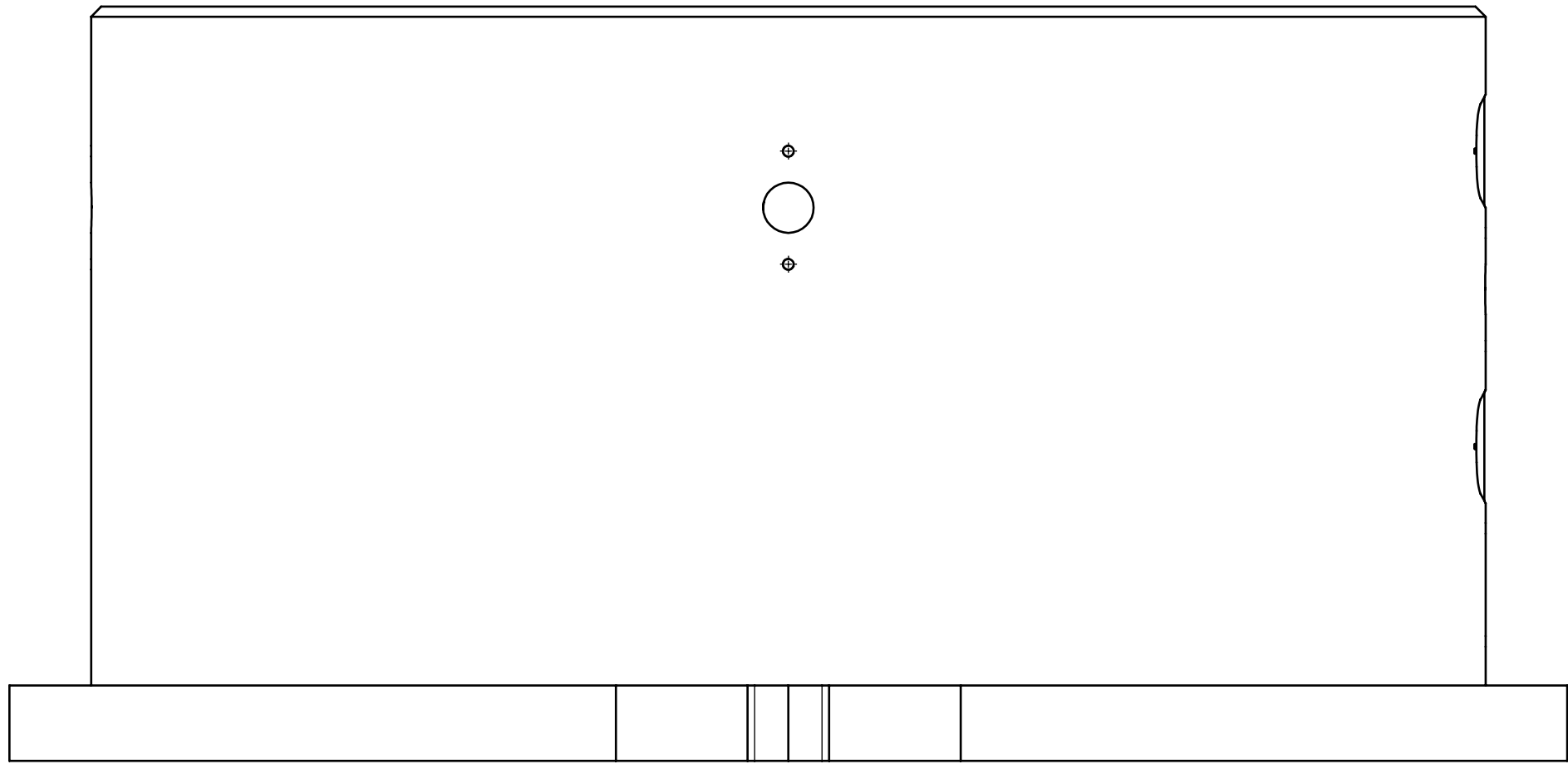


Rev.	Project	Task	Rev. date	Rev. by	Rev. by
01	Robot stand	Robot stand	2022-02-04	Michaels	Michaels
02	Robot stand	Robot stand	2022-02-04	Michaels	Michaels
03	Robot stand	Robot stand	2022-02-04	Michaels	Michaels
04	Robot stand	Robot stand	2022-02-04	Michaels	Michaels
05	Robot stand	Robot stand	2022-02-04	Michaels	Michaels



where nothing else	Status	dimension	weight
in mm	in mm	in mm	in kg
reference: DIN ISO 2768-mS	reference: DIN ISO 2768-mS	reference: DIN ISO 2768-mS	reference: DIN ISO 2768-mS
tolerance: DIN EN ISO 13715	tolerance: DIN EN ISO 13715	tolerance: DIN EN ISO 13715	tolerance: DIN EN ISO 13715
edge: DIN EN ISO 13715	edge: DIN EN ISO 13715	edge: DIN EN ISO 13715	edge: DIN EN ISO 13715
0.5	0.5	0.5	0.5
1.5	1.5	1.5	1.5
2.5	2.5	2.5	2.5
4.0	4.0	4.0	4.0
6.3	6.3	6.3	6.3
10.0	10.0	10.0	10.0
16.0	16.0	16.0	16.0
25.0	25.0	25.0	25.0
40.0	40.0	40.0	40.0
63.0	63.0	63.0	63.0
100.0	100.0	100.0	100.0
160.0	160.0	160.0	160.0
250.0	250.0	250.0	250.0
400.0	400.0	400.0	400.0
630.0	630.0	630.0	630.0
1000.0	1000.0	1000.0	1000.0

YASKAWA	dimension	weight
reference: DIN ISO 2768-mS	reference: DIN ISO 2768-mS	reference: DIN ISO 2768-mS
tolerance: DIN EN ISO 13715	tolerance: DIN EN ISO 13715	tolerance: DIN EN ISO 13715
edge: DIN EN ISO 13715	edge: DIN EN ISO 13715	edge: DIN EN ISO 13715
0.5	0.5	0.5
1.5	1.5	1.5
2.5	2.5	2.5
4.0	4.0	4.0
6.3	6.3	6.3
10.0	10.0	10.0
16.0	16.0	16.0
25.0	25.0	25.0
40.0	40.0	40.0
63.0	63.0	63.0
100.0	100.0	100.0
160.0	160.0	160.0
250.0	250.0	250.0
400.0	400.0	400.0
630.0	630.0	630.0
1000.0	1000.0	1000.0